₽EMKO

PID HOT RUNNER CONTROL UNIT



Eco HR

Eco HR PID Hot Runner Control Unit

- -3 digit process (PV) and 4 digit set (SV) display
- Process input (TC.RTD)
- Programmable ON/OFF, P, PI, PD and PID control forms
- -Adaptation of PID Coefficients to the system with Self-Tune and Auto-Tune
- Programmable Heating or Cooling Functions for Control Output
- Digital input for activate the 2nd set value (optional)
- Selectable Alarm Functions for Alarm Output
- Serial RS485 Communication (optional)

Eco series temperature controllers are designed for measuring and controlling a temperature value. They can be used in many applications with their TC and RTD temperature measurement input, multi-function control outputs, selectable alarm

 $They are \, mainly \, used \, in \, glass, \, plastic, \, petro-chemistry, \, textile, \, automotive \, and \,$ machine production industries. Accurate and advanced controlling is performed with selectable ON-OFF, P. PI, PD, PID and Self Tune/AutoTune PID functions.

SPECIFICATIONS

Process Input: TC, RTD

Thermocouple (TC): J. K. R. S. Tand L (IEC584.1)(ITS90)

Thermoresistance (RTD): Cu-50 and PT-100 (IEC751)(ITS90)

Measurement Range: Please refer to process input type selection in process menu parameters section.

Accuracy:

Thermocouple (TC):(±0.25% of full scale or ±3°C, which one is greater)±1 digit max

Thermoresistance (RTD): $(\pm 0.25\% \text{ of full scale or } \pm 2^{\circ}\text{C}$, which one is greater) ± 1 digit max

Cold Junction Compensation: Automatically ±0.1°C/1°C

Line Compensation: Maximum 10 Ohm Sensor Break Protection: Upscale

Sampling Cycle: 0.1 second

Input Filter: Programmable

Control Form: ON/OFF, P, PI, PD or PID (Control form can be programmed by the

OUTPUT

Process Output: Relay (5A@250V~ at resistive load) or SSR Driver Output (Maximum 10mA, Max. 12V===)

Alarm Output: Relay (5A@250V~ at resistive load)

SUPPLY VOLTAGE

230V~ (±15%) 50/60Hz - 2VA 115V~ (±15%) 50/60Hz - 2VA

10...30V==-2W

(It must be determined in order)

DISPLAY

Process Display: 16 mm Red 3 digit LED Display Set Value Display: 9 mm Orange 4 digit LED Display

Led Indicators: PO1 (SSR Process Output Status Led), PO2 (Relay Process Output Status Led), AL1, AL2 (Alarm Output Status Leds), °C, °F LEDs

ENVIRONMENTAL RATINGS and PHYSICAL SPECIFICATIONS

Operating Temperature: 0...50°C Humidity: 0-90%RH (none condensing) Protection Class: IP65 at front, IP20 at rear

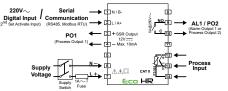
Weight: 150 gr.

Dimension: 48 x 48 mm, Depth: 86.5 mm

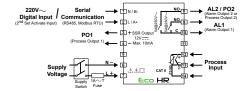
Panel CutOut: 46 x 46 mm

Electrical Wirings

The Device with One Relay:



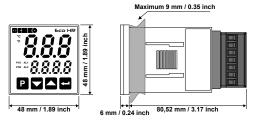
The Device with Two Relays:



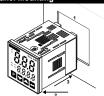
CE

To reduce the effect of electrical noise on device, low voltage line (especially sensor input cable) wiring must be separetely from high current and voltage line. If possible. use shielded cable and shield must be connected to ground only one side

Dimensions



Panel Mounting

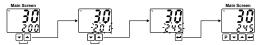


- 1- Before mounting the device in your panel, make sure that the cutout is of the right size.
- 2- Check front panel gasket position.
- 3- Insert the device through the cutout. If the mounting clamps are on the unit, put out them before inserting the unit to the panel.



- 4- Insert the mounting clamps to the two of designated holes that located four sides of
- 5- Drag the mounting clamps in direction 5 until the device completely immobile within the panel.
- 6- In order to remove device push on the mounting clamp as shown with arrow 6 and

Access and Change Set Values



Press increment or decrement button to change process set value.

Press Enter button to save new set value and return the main screen

Temperature Set Value Parameter (Default: 200) MODBUS ADDRESS: 40000

Note-1: User can exit from set value section without saving the values by pressing P button. If no

operation for 120 seconds, device automatically exits from Set Value section Note-2: Set value can be adjusted between Set Value Low and High Limit (5#4 - 5#6)

during 5 sec. out MERE P UΠ 0 -P PL Sbo Shd 560

Easy Access Diagram For Program Parameters

Press Program P button Enter Password with increment Approve password or decrement buttons with Enter button bRu PK .8 PÄ Ä RL Ru

on

·oF

-P

*1 - ON/OFF Hysteresis parameter is not seen unless [n5 parameter is set as onof.

ond

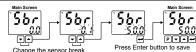
- *2 Soft Start parameters(55t, 5£a, 5£t) are not seen unless £a5 parameter is set as \$\rho_i d\$.
 *3 Soft Start Control Output and Soft Start Control Time parameters are not seen if \$5\rak{t}\$ parameter.
- is set as no. *4 - PID control parameters are not seen unless los 5 parameter is set as los 6.

-0

- *5 Alarm-2 parameters are not seen if out parameter is set as < 1.9. Also parameters are not seen on devices with one relay.
- *6 Communication parameters are not seen on devices without RS485 communication.
- *7 If PPS is different from 0 and user enters to program menu without entering the password Pr & menu is not seen.

Note: User can exit from any parameter screen without saving the values by pressing P button. If no operation for 120 seconds, device automatically return to main screen

Easy Access Diagram For Sensor Break Output Value From Main Screen



output value with increment or decrement buttons

new sensor break output value and exit.

Note1: User can exit from parameter screen without saving the values by pressing P button. If no operation for 120 seconds, device automatically exits from parameter screen

Note2: Sensor break output value can be adjusted on programming section

Activate Second Set



during 1 sec. and activate second set value

is activated Set2 value blinks

Press program button P during 1 sec again to activate main set value

Tune Operation

Starting the Tune operation

1- Enter to the $\xi u n \xi$ parameter in $P \cdot d$ menu and select $S \xi \xi F$ or RUE₀, then press de button for saving parameter and turn to main screen. Or easily press button for 3 seconds* in main screen.

2- Observe that $\xi u \cap \xi$ blinks in set display.

Canceling Tune operation

1- If sensor breaks:

If tune operation can not be completed in 8 hours;

3- While heating self tune is running, if process value becomes greater than process set value:

4- While cooling self tune is running, if process value becomes less than process set value;

5- While tune operation is running, if user changes the process set

value: 6- While tune operation is running, if user changes the bunk

parameter in p d menu; Then tune operation is canceled, device continues to run with former

PID parameters without changing PID parameters

Introduction Brochure, ENG EcoHR 01 V03 01/19

Pr 5: Process Menu Parameters

5 ξ ξ: 2nd Set value. As long as digital input of the device is active, 2nd set value is used as process set value. If digital input is passive, device use previous set value as process set value. (Default: 100) Modbus Address: 40004

P (n: Process input type selection; (Default: (1) Modbus Address: 40004

- @: J type (Fe,Cu,Ni) Thermocouple , -199°C,900°C : -199°F,999°F
- #: J type (Fe Cu Ni) Thermocouple . -19.9°C 99.9°C : -19.9°E99.9°F
- 2: K type (Ni,Cr,Ni) Thermocouple , -199°C,999°C ; -199°F,999°F
- 3: K type (Ni,Cr,Ni) Thermocouple , -19.9°C,99.9°C ; -19.9°F,99.9°F
- 4: R type (Pt13%RhPt) Thermocouple . 0°C 999°C : 32°E 999°F
- 5: R type (Pt13%RhPt) Thermocouple , 0.0°C,99.9°C ; 32.0°F,99.9°F
- 8: S type (Pt10%RhPt) Thermocouple, 0°C,999°C: 32°F,999°F
- 7: S type (Pt10%RhPt) Thermocouple , 0.0°C,99.9°C : 32.0°F.99.9°F
- 8: T type (Cu,Cu,Ni) Thermocouple , -199°C,400°C ; -199°F,752°F
- 9: T type (Cu,Cu,Ni) Thermocouple , -19.9°C,99.9°C ; -19.9°F.99.9°F
- 10: L type (Ni,Cr,Co / Ni,Fe,Mn,Cu) Thermocouple , -150°C,800°C ; -199°F,999°F 11: L type (Ni, Cr, Co / Ni, Fe, Mn, Cu) Thermocouple . -19.9°C .99.9°C : -19.9°F .99.9°I
- 12: Cu-50 . -199°C 200°C : -199°F 392°F
- 13: Cu-50 , -19.9°C,99.9°C ; -19.9°F.99.9°F
- 14: Pt-100 . -199°C 650°C : -199°E 999°E
- /5: Pt-100 . -19.9°C.99.9°C : -19.9°F.99.9°F
- Unit Selection. of or or can be chosen. (Default: or) Modbus Address: 40006 PLo: Operation Scale minimum (Low Limit) value. It changes according to the process input type and scale. (Default: -199) Modbus Address: 40007
- PuP: Operation Scale maximum (High Limit) value. It changes according to the
- process input type and scale. (Default: 900) Modbus Address: 40008 5#L: Process Set value Low Limit. Minimum set value is defined with this parameter
- It can be adjusted between Operation Scale minimum and maximum (p; p p, p) values. (Default: -199) Modbus Address: 40009
- 5#u: Process Set value High Limit. Maximum set value is defined with this parameter It can be adjusted between Operation Scale minimum and maximum $(\rho_{L\rho} - \rho_{\mu}\rho)$ values. (Default: 900) Modbus Address: 40010
- PoF: Display offset for process value. It can be adjusted from -10% of scale to 10% of scale. It is added to the process display value. (Default: 0) Modbus Address: 40011
- رجيد المجاب الم

Ent: Control Menu Parameters

- out: This parameter determines, which output will be Process control output. If r L y is chosen, process output is relay output, if 55r is chosen, process output is SSR output. (Default: 55r) Modbus Address: 40017
- Pr 5: Process Type Selection. It can be #£8£(Heating) or Loot(Cooling).(Default:#£8£) Modbus Address: 40018
- En5: Process Control Type Selection. It can be one F or P .d. (Default: P .d.) Modbus Address: 40019
- 835: Hysteresis value. It can be adjusted from %0 to %50 of the Scale (PuP PL o If $f \circ S = g \circ F$, then this parameter can be seen. (Default: 3) Modbus Address: 40020 566: Sensor Break Output Value. It can be adjusted from %0 to %100. (Default: 0.0) Modbus Address: 40021
- 56d: The choice of displayed text on process value display when sensor is broken It can be 55c or oco. (Default: 55c) Modbus Address: 40022
- 558: Soft Start Set value. Device operates in Soft Start mode, until the temperature reaches Soft Start set value. If no is selected, Soft Start mode is disabled. (Default: no) Modbus Address: 40023
- 5(o: Soft Start Control Output. This parameter determines soft start mode control output percentage. It can be adjusted from %10 to %90. (Default: 10.0) Modbus Address: 40024
- 5£: Soft Start Control Time. This parameter determines soft start mode control time (Default: 1.0) Modbus Address: 40025

೪ ಚ: PID Menu Parameters

PID menu parameters can be seen only if [n] parameter is Pnd.

- Eun: If tune parameter is set to \$\$£\$ or \$\$\$\$\$0, device start to calculate PID parameters automatically. (Default: no) Modbus Address: 40029
- Pr b: Proportional band. It can be adjusted from %1.0 to %100.0. (Default: 10.0) Modbus Address: 40030
- ادره: Integral Time. It can be adjusted from 0 to 3600 second. (Default: 100) Modbus Address: 40031
- ₹ Derivative Time. It can be adjusted from 0.0 to 999.9 second. (Default: 25.0) Modbus Address: 40032
- ξξο: Output Control Period. It can be adjusted from 0.5 to 150 second. (Default: 1.0) Modbus Address: 40033
- S_0F : Set value offset. (Set $+S_0F$) is used as set value in PID calculations. This parameter is used for shifting the proportional band. It can be adjusted from (-PuP/2) to (PuP/2). (Default: 0) Modbus Address: 40034

8t 1: Alarm-1 Menu Parameters

- RH 1: Alarm-1 hysteresis value. It can be adjusted from %0 to %50 of the scale
- (PuP PLo). (Default: 0) Modbus Address: 40039
- RE 1: Alarm-1 type selection. (Default: PH .R) Modbus Address: 40040
- Rt. 1: Alarm-1 set low limit parameter. It can be adjusted from operation scale minimum to alarm-1 set high limit. (Default: 0) Modbus Address: 40041
- Ru I: Alarm-1 set high limit parameter. It can be adjusted from alarm-1 set low limit to operation scale minimum. (Default: 500) Modbus Address: 40042
- on t: Alarm-1 on Delay Time. It can be adjusted from 0 to 9999 seconds. (Default: 0) Modbus Address: 40043
- of I: Alarm-1 off Delay Time. It can be adjusted from 0 to 9998 seconds. If it is higher than 9998, ¿ ¿ [H is seen on the screen and alarm latching output is selected. In alarm latching output mode in order to make passive alarm outputs, press enter 🖨 button at main screen. (Default: 0) Modbus Address: 40044

8t 2: Alarm-2 Menu Parameters (Only for devices with two re

Alarm-2 menu parameters can be seen only if out parameter is 55-

- 852: Alarm-2 set value. (Default: 400) Modbus Address: 40048
- 882: Alarm-2 hysteresis value. It can be adjusted from %0 to %50 of the Scale (PuP - Pl a). (Default: 0) Modbus Address: 40049
- 8 2: Alarm-2 type selection. (Default: PK .8) Modbus Address: 40050
- 81.2. Alarm-2 set low limit parameter. It can be adjusted from operation scale minimum to alarm-2 set high limit (Default: 0) Modbus Address: 40051
- 8...2. Alarm-2 set high limit parameter. It can be adjusted from alarm-2 set low limit to operation scale maximum. (Default: 500) Modbus Address: 40052
- one: Alarm-2 on delay time. It can be adjusted from 0 to 9999 seconds. (Default: 0) Modbue Addrose: 40053
- ο Ε 2: Alarm-2 off delay time. It can be adjusted from 0 to 9998 seconds. If it is higher than 9998, LEEM is seen on the screen and Alarm Latching Output is selected. In alarm latching output mode in order to make passive alarm outputs, press enter button at main screen. (Default: 0) Modbus Address: 40054.

Con: Communication Parameters (Only for devices with RS-485 com.)

Rdr: Communication accessing address of device. (Default: 1) Modbus Address: 40058

- bคือ: Communication Baud Rate. (Default: 3) Modbus Address: 40059
- 0: 1200 Baud Rate. 1: 2400 Baud Rate.
- 2: 4800 Baud Rate.
- 3: 9600 Baud Rate.
- 4: 19200 Baud Rate.
- 5: 38400 Baud Rate.
- Par: Parity Selection for Communication, (Default: 0) Modbus Address: 40060 # No Parity.
- # Odd Parity
- 2. Even Parity
- 58 b: Stop Bit Selection for Communication. (Default: 0) Modbus Address: 40061
- 0: 1 Ston Bit # 2 Stop Bit

Prt: Protecion Menu Parameters

PPS: Password for accessing to the programming section. It can be adjusted from 0 to 9999. If PPS is 0, password screen is not seen. If PPS is different from 0 and user enters to the menu pages without entering the password, all the menus can be observed except protection menu Pr L. But device does not allow to do any changes in parameters. (Default: 0) Modbus Address: 40065

udf: User default parameters. This parameter is used for saving all parameters to restore later or restore all parameters saved before. If ££ is chosen, all parameters saved before are restored. If \$\xi_{\epsilon}\$ is chosen, all parameters saved to restore later. If no is chosen, nothing is changed. (Default: ng) Modbus Address: 40066 F dF: This parameter is used for restore factory defaults. If GEE is chosen, factory

defaults parameters restored. If no is chosen, nothing is changed. (Default: no)

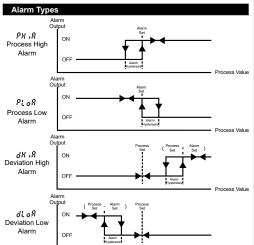
Remove all input/output connections on terminals before restoring Remove all input/output connect parameters to user/factory defaults.

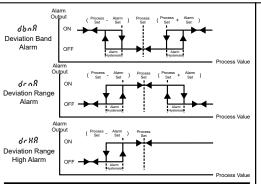
Modbus Addresses of Device Operation Info. (Read Input Register)

Modbus Address: 30000 Displayed Temperature Value Modbus Address: 30001 Status of LEDs; bit.1 AURI, bit.2 AURI bit.9 IC

bit.10 °E. bit.11 PO2 bit.12 PO1

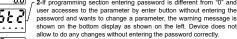
Modbus Address: 30002 Status of Device: bit 0 Sensor Break Status





Error Messages

- 1-Sensor failure in analog inputs. Sensor connection is wrong or there is no sensor connection 0.0 2-If programming section entering password is different from "0" and

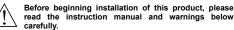


- 3-If value that is read from the analog input is lower than process set low limit parameter value $(P_{l,0})$, value on the top display starts to blink as shown on the picture. - 4-If value that is read from the analog input is higher than process set

high limit parameter value (P.,P), value on the top display starts to blink as shown on the nicture - 5-If value that is read from the analog input is lower than sensor scale low limit, value on the top display starts to blink as shown on the

6-If value that is read from the analog input is higher than sensor scale high limit, value on the top display starts to blink as shown on the 200 nicture

Installation



In package.

-One piece unit

-Two pieces mounting clamp

One piece instruction manual

A visual inspection of this product for possible damage occured during shipment is recommended before installation. It is your responsibility to ensure that qualified mechanical and electrical technicians install this product

If there is danger of serious accident resulting from a failure or defect in this unit, power off the system and the electrical connection of the device from the system.

The unit is normally supplied without a power switch or a fuse. Use power switch and fuse as required.

Be sure to use the rated power supply voltage to protect the unit against damage and to prevent failure.

Keep the power off until all of the wiring is completed so that electric shock and trouble with the unit can be prevented

Never attempt to disassemble, modify or repair this unit. Tampering with the unit may results in malfunction, electric shock or fire.

Do not use the unit in combustible or explosive gaseous atmospheres. During the equipment is putted in hole on the metal panel while mechanical installation some metal burrs can cause iniury on hands, you must be careful.

Montage of the product on a system must be done with it's mounting clamp. Do not do the montage of the device with inappropriate mounting clamp. Be sure that device will not fall while doing the

It is your responsibility if this equipment is used in a manner not specified in this instruction manual.

Warranty

EMKO Elektronik warrants that the equipment delivered is free from defects in material and workmanship. This warranty is provided for a period of two years. The warranty period starts from the delivery date.

This warranty is in force if duty and responsibilities which are determined in warranty document and instruction manual performs by the customer completely.

Maintenance

Repairs should only be performed by trained and specialized personnel. Cut power to the device before accessing internal parts. Do not clean the case with hydrocarbon-based solvents (Petrol. Trichlorethylene etc.). Use of these solvents can reduce the mechanical reliability of the device. Use a cloth dampened in ethyl alcohol or water to clean the external plastic case.

Other Informations

Manufacturer Information:

Emko Elektronik Sanayi ve Ticaret A.Ş.

Demirtaş Organize Sanayi Bölgesi Karanfil Sk. No:6 16369 BURSA/TURKEY

Phone: +90 224 261 1900 Fax: +90 224 261 1912

Repair and Maintenance Service Information:

Emko Elektronik Sanayi ve Ticaret A.Ş.

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BURSA/TURKEY Phone: +90 224 261 1900

Fax : +90 224 261 1912 Ordering Information

Eco HR (48x48 DIN 1/16) A Dimension

4 48x48 DIN 1/16

B Supply Voltage

1 100-240V~ (±%15) 50/60Hz 3 115V_{\(\sigma\)} (+%15) 50/60Hz 5 230V~ (±%15) 50/60Hz

6 10...30V... 9 Customer

C Outputs-1

1R 1 x Relay Output (5A@250V~ at Resistive Load) (NO,C)

2R 2 x Relay Output (5A@250V~ at Resistive Load) (NO,NO,C)

D Outputs-2 S SSR Driver Output (Max. 10mA, Max. 12V===)

E Communication

0 None 485 RS-485 Communication



Before commissioning the device, parameters must be set in accordance with desired use. Incomplete or incorrect configuration can cause dangerous stigations.



Because of limited mechanical life of relay output contact, SSR output is recommended which the device use PID control algoritm. The device with ON/OFF control algoritm, hysteresis parameter must be set a suitable value for your system, to avoid too much relay



=== → Vdc,

Thank you very much for your preference to Thank you very much for your preference to use Emko Elektronik products, please visit our Your Technology Partner web page to download detailed user manual.

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